

**AMENDMENTS TO THE SPECIFICATION**

Please replace the abstract of the invention, which is found on page 12 of the specification, with the following amended abstract:

-- In origin adjustment between two members which rotate relatively at a joint of an industrial robot, an origin adjustment apparatus is provided which is inexpensive and highly accurate and which requires extremely few man hours. In addition, an origin adjustment apparatus is provided which is so small in size as to be easily used even on a distal end shaft of a wrist of the robot and which requires no special signal line for origin adjustment. A mount member (23) where a positioning member (22) is embedded and a guide portion (24) along which the positioning member (22) slides in such a manner as to protrude are provided on either one or both of the two members which rotate relatively.--